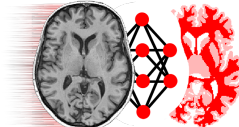




Uncertainty in multitask learning: joint representations for probabilistic MR-only radiotherapy treatment planning

Felix Bragman, Ryutaro Tanno, Zach Eaton-Rosen, Wenqi Li, David J. Hawkes, Sebastien Ourselin, Daniel C. Alexander, Jamie R. McClelland and M. Jorge Cardoso

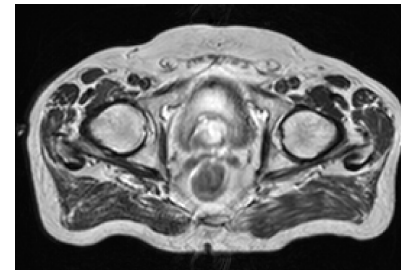


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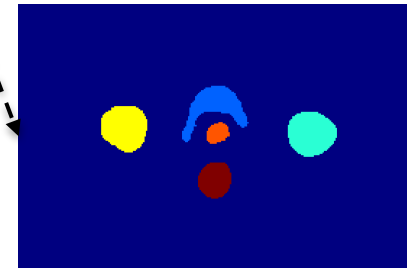
21st International Conference on Medical Image Computing
& Computer Assisted Intervention (MICCAI 2018)
September 2018, Granada

MR-only radiotherapy treatment planning

- MR-only radiotherapy treatment planning requires the simultaneous
 - a) synthesis of a CT scan (synCT) from MRI
 - b) segmentation of organs at risk (OAR) from MRI
- Main goal
 - a) Multi-task learning for simultaneous regression and segmentation
 - b) Probabilistic deep learning to acquire uncertainties in the prediction of the network



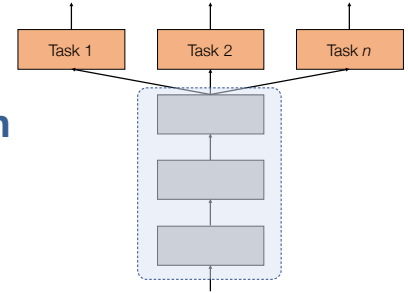
CT synthesis



Organ segmentation

Multi-task feature learning

- Medical image analysis aims to learn a **common anatomical representation**
- Learn a non-linear mapping from this feature space to minimise a loss
- *How to minimise this loss in a multi-task setting?*



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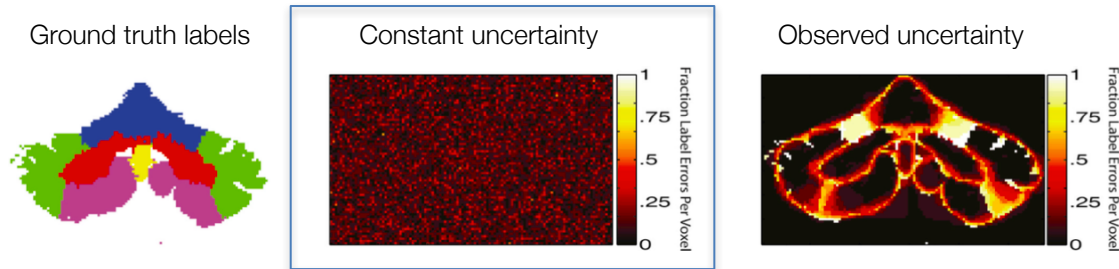
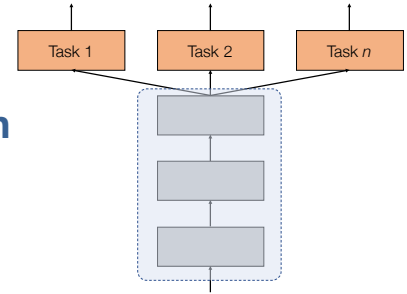
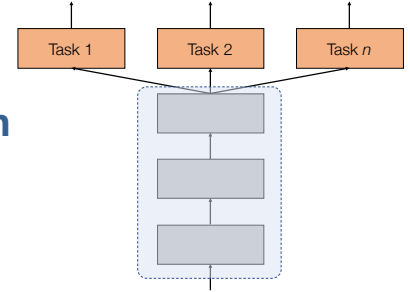


Figure adapted from Asman *et. al.*, IEEE TMI 2011

- Allows us to exploit this property (heteroscedasticity) for a natural mechanism for weighting task losses

Multi-task feature learning

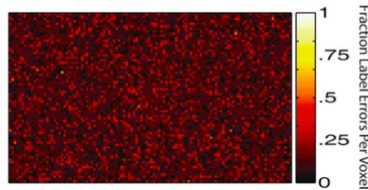
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Ground truth labels



Constant uncertainty



Observed uncertainty

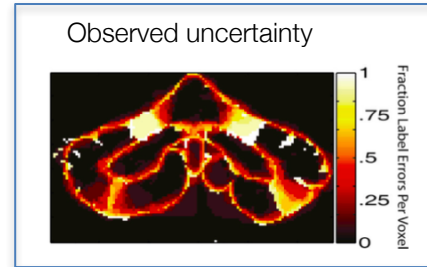
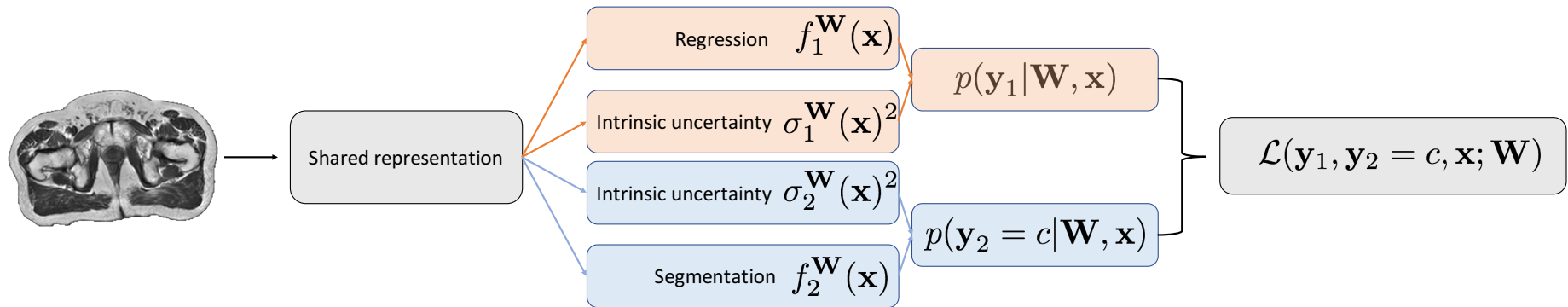


Figure adapted from Asman *et. al.*, IEEE TMI 2011

- Allows us to exploit this property (heteroscedasticity) for a natural mechanism for weighting task losses

Our contribution

- Probabilistic dual-task network with hard-parameter sharing
 - Shared representation network + regression and segmentation specific branches
- Predict task-specific heteroscedastic uncertainty for spatially adaptive task loss weighting
- Approximate Bayesian inference to also capture uncertainty in the model weights



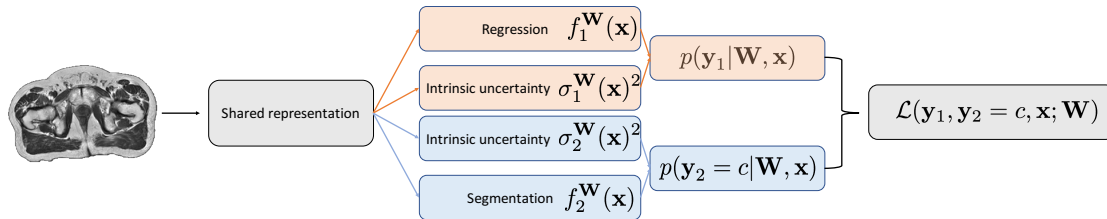
Our contribution

- Multi-task likelihood:

$$\mathcal{L}(\mathbf{y}_1, \mathbf{y}_2 = c, \mathbf{x}; \mathbf{W}) = \frac{\|\mathbf{y}_1 - f_1^{\mathbf{W}}(\mathbf{x})\|^2}{2\sigma_1^{\mathbf{W}}(\mathbf{x})^2} + \frac{\text{CE}(f_2^{\mathbf{W}}(\mathbf{x}), \mathbf{y}_2 = c)}{2\sigma_2^{\mathbf{W}}(\mathbf{x})^2} + \log\left(\sigma_1^{\mathbf{W}}(\mathbf{x})^2 \sigma_2^{\mathbf{W}}(\mathbf{x})^2\right)$$

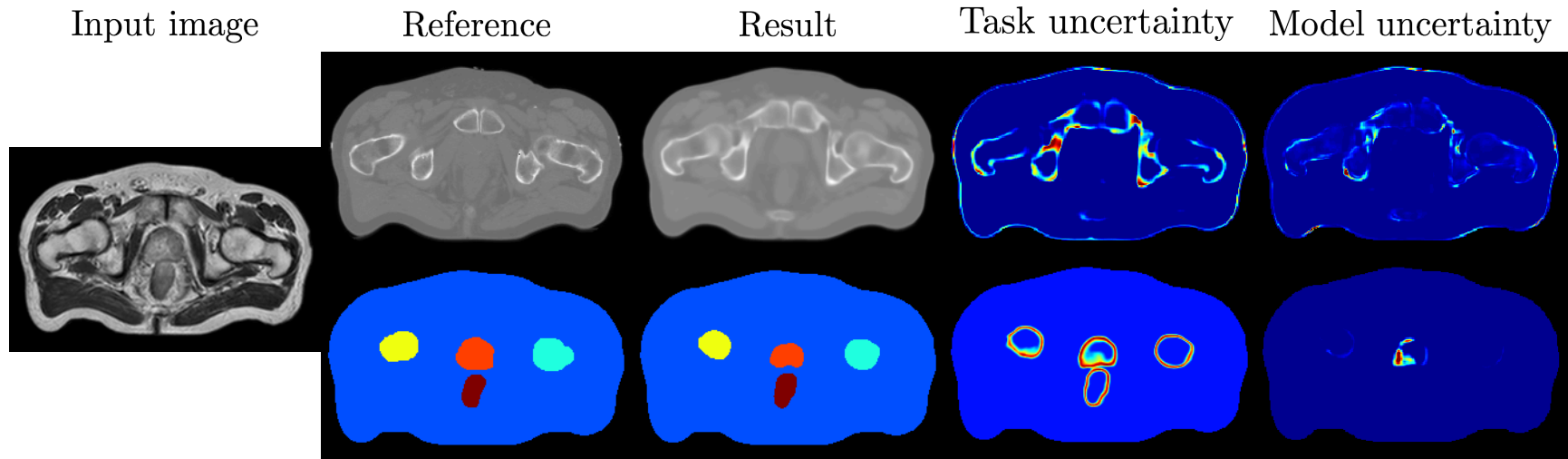
- Separate networks to predict:

- Regression and segmentation per voxel: $f_1^{\mathbf{W}}(\mathbf{x})$, $f_2^{\mathbf{W}}(\mathbf{x})$
- Spatially adaptive weighting using heteroscedastic uncertainty: $\sigma_1^{\mathbf{W}}(\mathbf{x})^2$, $\sigma_2^{\mathbf{W}}(\mathbf{x})^2$



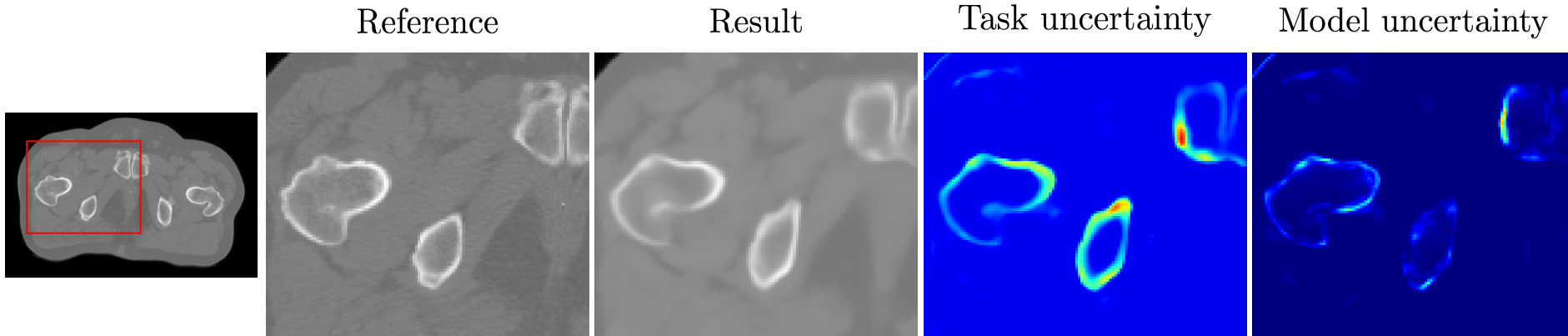
Experiment on 15 prostate cancer patients

- 3-fold cross-validation for training and testing



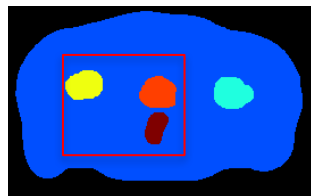
Experiment on 15 prostate cancer patients

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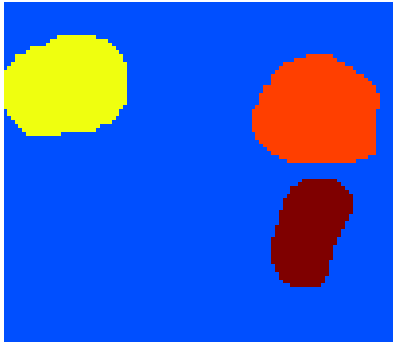


Experiment on 15 prostate cancer patients

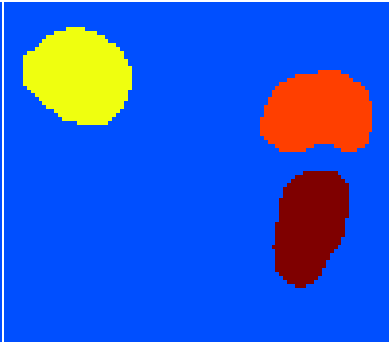
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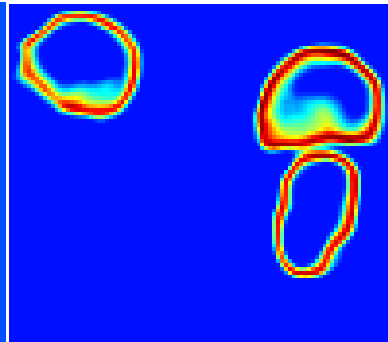
Reference



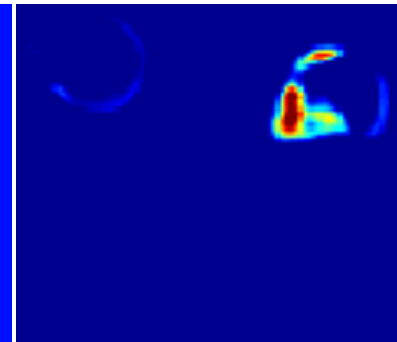
Result



Task uncertainty



Model uncertainty

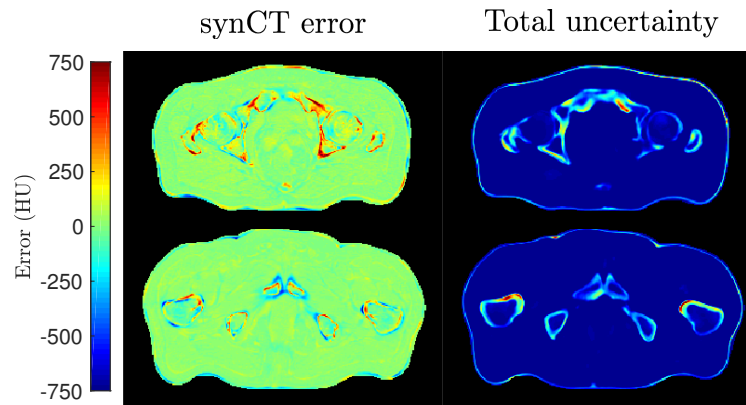


Main results

1. Joint modelling of heteroscedastic uncertainty and test-time variance in a multi-task setting **outperforms** homoscedastic weighting and all other models

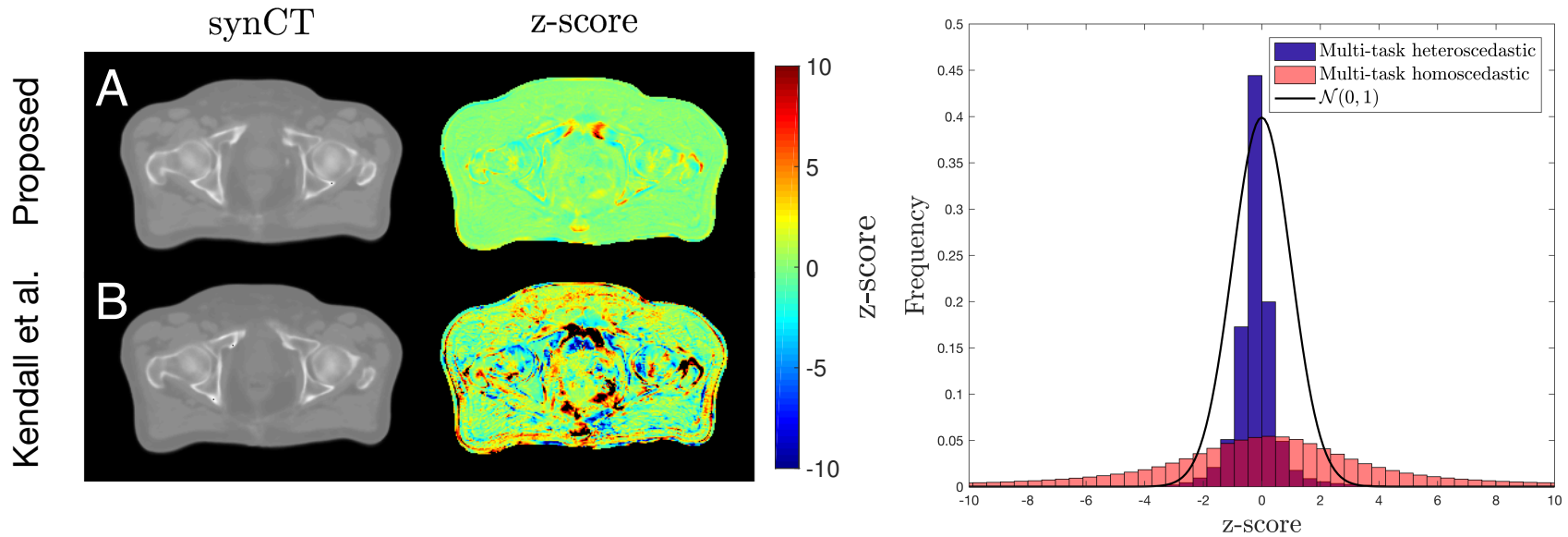
| Models | All | Bone | <i>L</i> femur | <i>R</i> femur | Prostate | Rectum | Bladder |
|---|-----------|-----------|----------------|----------------|-----------|------------|-----------|
| Regression - synCT - Mean Absolute Error (HU) | | | | | | | |
| Multi-task + homoscedastic weighting | 44.3(3.1) | 126(14.4) | 74.0(19.5) | 73.7(17.1) | 29.4(4.7) | 58.4(48.0) | 18.2(3.5) |
| Our method | 43.3(2.9) | 121(12.6) | 69.7(13.7) | 67.8(13.2) | 28.9(2.9) | 55.1(48.1) | 18.3(6.1) |

2. Total uncertainty provides a mechanism for automated quality control and assurance



Main results

- Well calibrated variance from our model (A) compared those with constant task uncertainty (B)



Thanks!

- More results in poster!
- Code to be released within NiftyNet (pip install niftynet)
- Poster #101 tonight from 18:00 to 19:30!

Poster M-101



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